Unranking of Reduced Ordered Binary Decision Diagrams

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Workshop Computational Logic and Applications

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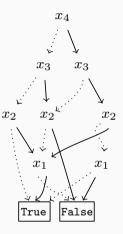
\*GREYC @ Normandie University

Let f be a Boolean function in k variables.

A *Binary Decision Diagram* is a compact representation of *f* allowing to evaluate it efficiently.

It is based on some divide-and-conquer principle.

[Wegener00]: Branching Programs and Binary Decision Diagrams [Knuth11]: The Art of Computer Programming (vol.4)

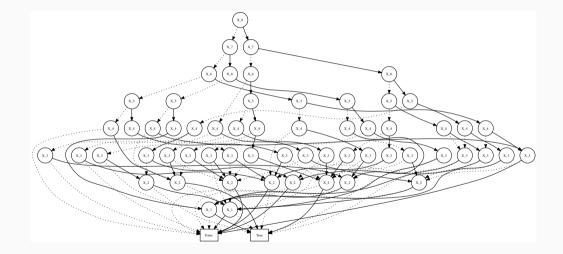


We are interested in Reduced Ordered Binary Decision Diagrams, denoted ROBDDs. We take a point of view of a combinatorialist.

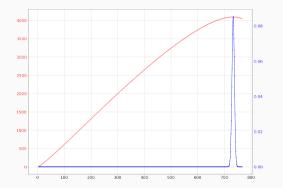
#### Shannon effect: ROBDD's size distribution



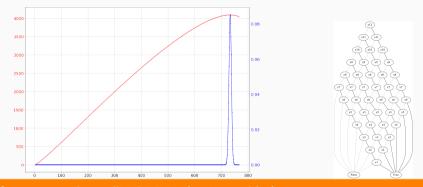
# Motivations: Building ROBDDs of small size



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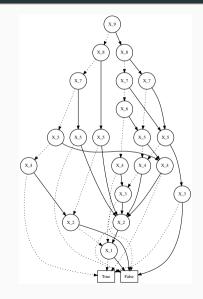
#### Motivations: Building ROBDDs of small sizes



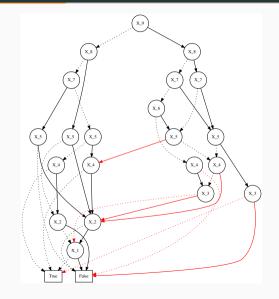
#### Specific functions with small ROBDDs (in *k* variables):

	$\ell$ th	resho	old fi	uncti	ons:	$7 \leq$	$k \leq 1$	12;	$1 \leq k$	$\ell \leq k$		
- addition in <i>k</i> bits,		14	17	18	17	14						
- read-once fcts,				22	22							
- symmetric fcts:	11		23		27		23		11			
	12				32	32				12		
$O(k^2)$ .	13	22		34	37	38	37	34		22	13	
	14	24	32		42	44	44	42		32	24	14

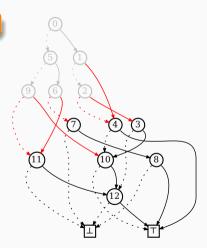
#### Why does the enumeration be difficult?



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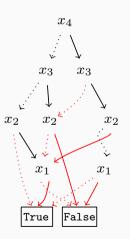


• Combinatorial preliminaries



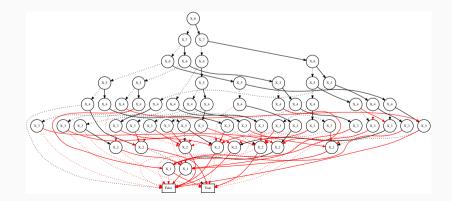
#### Outline of the talk

- Combinatorial preliminaries
- Iterative counting



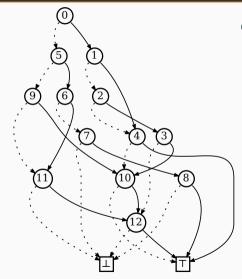
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- Unranking a ROBDD



# Combinatorial preliminaries

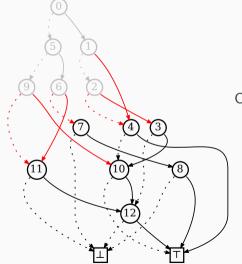
#### Focus on DAGs $\approx$ ROBDDs



Concepts:

- low/high child
- size
- layers
- constraints:
  - useful node property
  - descendants unicity in a given layer
  - acyclicity
  - accessibility
- profile [1, 2, 3, 3, 3, 1, 2]
- reverse postorder traversal

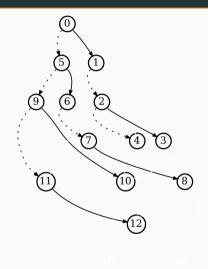
#### Multientry ROBDD



Concepts:

- removing upper layers multientry ROBDD
  - keeping destination of red edges as a multiset {3, 4, 4, 7, 10, 11, 11}

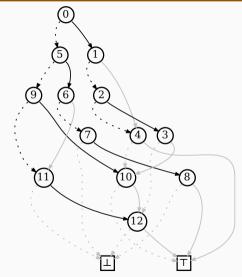
### Spine of a ROBDD



Concepts:

- the spine of a ROBDD spanning tree given by a depth-first search
  - $\bullet \ \Rightarrow {\sf tree} \ {\sf edges}$

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Concepts:

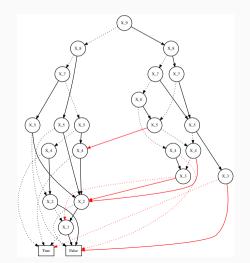
the spine of a ROBDD

spanning tree given by a depth-first search

- $\bullet \ \Rightarrow {\sf tree \ edges}$
- non-tree edges

# **Iterative counting**

#### In my CLA'20 talk [Latin'20]: recursive counting



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The time complexity (in the number of arithmetic operations) for partitioning the Boolean functions in k variables according to their ROBDD size is

 $\Omega(M_k^{1.5 \cdot \log M_k}),$ 

where  $M_k$  if the largest ROBDD on k variables.

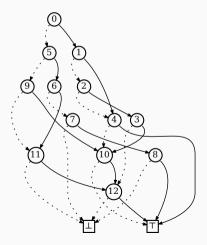
$$(M_k)_{k=1,\ldots,12} = (3, 5, 7, 11, 19, 31, 47, 79, 143, 271, 511, 767)$$

We have  $\frac{2^k}{k} \le M_k \le 2 \cdot \frac{2^k}{k}$  as k tends to infinity.

In practice, we computed the partition for k = 8 in about 2 hours on a personal computer with a python implementation and for k = 9, in several days using a fast computer with a C++ implementation.

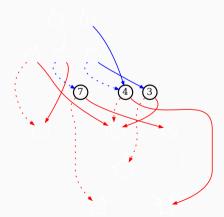
Today: iterative counting

through inclusion-exclusion principle



Today: iterative counting

through inclusion-exclusion principle



- 7 incoming edges
- 3 nodes
- 9 outgoing edges

Today: iterative counting

through inclusion-exclusion principle

The time complexity (in the number of arithmetic operations) for partitioning the Boolean functions in k variables according to their ROBDD size is

 $O(M_k^4 \cdot \log M_k),$ 

where  $M_k$  if the largest ROBDD on k variables.

 $(M_k)_{k=1,\ldots,12} = (3, 5, 7, 11, 19, 31, 47, 79, 143, 271, 511, 767).$ 

We have  $M_k \approx 2^k/k$  as k tends to infinity.

In practice, we compute the partition for k = 12, thus for the 2<sup>4096</sup> functions in about 6 hours on a computer with > 200GB of RAM.

#### cf. https://github.com/agenitrini/BDDgen

# Unranking a ROBDD

- Defining a total order over the structures (same number of Boolean variables and same size).
- 2. Constructing the structure only by using its rank.

- $\Rightarrow~$  This allows to build structures of a given size.
- $\Rightarrow\,$  This leads trivially to a uniform (by size) random sampler.

Inputs: rank r, size s, number of variables  ${\tt k}$ 

1. Select the profile;

Done by iteratively computing the number of nodes by layer.

Inputs: rank r, size s, number of variables k

- 1. Select the profile;
- 2. Build the spine;

Reverse postorder traversal gives information about non-tree edges.

Inputs: rank r, size s, number of variables k

- 1. Select the profile;
- 2. Build the spine;
- 3. Build the ROBDD;

Inorder traversal allows to decide the destination of non-tree edges.

Inputs: rank r, size s, number of variables k

- 1. Select the profile;
- 2. Build the spine;
- 3. Build the ROBDD;

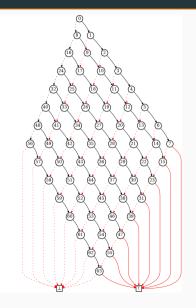
The unranking algorithm with inputs r, n, k satisfies:
O(k<sup>2</sup> n<sup>5</sup>) time complexity and O(n<sup>2</sup>) extra space for identifying the profile;
O(k<sup>2</sup> n<sup>3</sup>) time complexity to generate the ROBDD with a given profile.

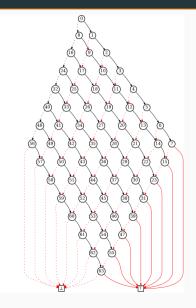
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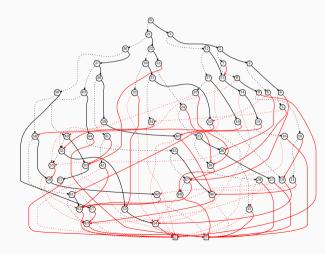
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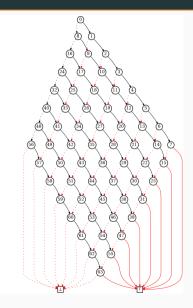
We can shortcut Step 1, or Step 1 and 2.

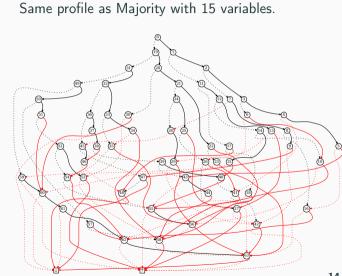


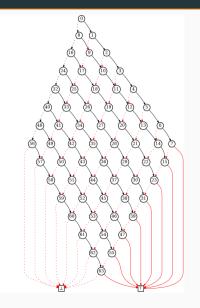


Same size as Majority with 15 variables.

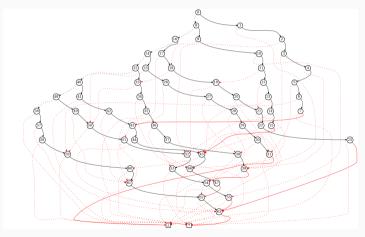




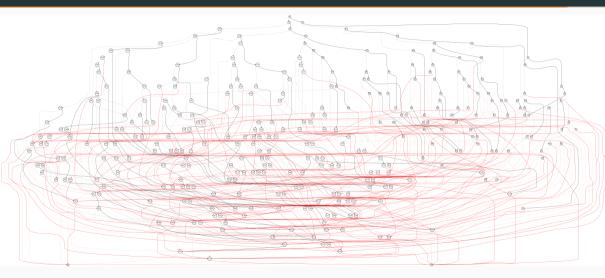




Same spine as Majority with 15 variables.



#### ROBDD gallery: same spine as Majority with 35 variables



#### Conclusion and future work

- Our combinatorial approach adapts very well.
  - subclasses of functions: ex. only with essential variables
  - other classes of BDDs (with other constraint rules)
    - OBDDs
    - Quasi-reduced BDDs
    - Zero-supressed BDDs
- In the future:
  - Combinatorial characterization of the class of spines?
  - Can we improve the time complexity for the counting/unranking methods?