Unranking of Reduced Ordered Binary Decision Diagrams

arXiv:2211.04938

Antoine Genitrini† with Julien Clément<sup>∗</sup>

Workshop Computational Logic and Applications

January 13, 2023

†LIP6 @ Sorbonne University <sup>∗</sup>GREYC @ Normandie University

Let f be a Boolean function in k variables.

A Binary Decision Diagram is a compact representation of f allowing to evaluate it efficiently.

It is based on some divide-and-conquer principle.

[Wegener00]: Branching Programs and Binary Decision Diagrams [Knuth11]: The Art of Computer Programming (vol.4)



We are interested in Reduced Ordered Binary Decision Diagrams, denoted ROBDDs. We take a point of view of a combinatorialist.

#### Shannon effect: ROBDD's size distribution



## Motivations: Building ROBDDs of small size



## Motivations: Building ROBDDs of small sizes



#### Motivations: Building ROBDDs of small sizes



#### Specific functions with small ROBDDs (in *k* variables):



## Why does the enumeration be difficult?



## Why does the enumeration be difficult?



## • Combinatorial preliminaries



## Outline of the talk

- Combinatorial preliminaries
- Iterative counting



## Outline of the talk

- Combinatorial preliminaries
- Iterative counting
- Unranking a ROBDD



# <span id="page-11-0"></span>[Combinatorial preliminaries](#page-11-0)

### Focus on DAGs ≈ ROBDDs



Concepts:

- low/high child
- size
- layers
- constraints:
	- useful node property
	- descendants unicity in a given layer
	- acyclicity
	- accessibility
- profile  $[1, 2, 3, 3, 3, 1, 2]$
- reverse postorder traversal

## Multientry ROBDD



Concepts:

- removing upper layers multientry ROBDD
	- keeping destination of red edges as a multiset {3, 4, 4, 7, 10, 11, 11}

## Spine of a ROBDD



Concepts:

- the spine of a ROBDD spanning tree given by a depth-first search
	- $\bullet \Rightarrow$  tree edges

## Spine of a ROBDD



#### Concepts:

• the spine of a ROBDD

spanning tree given by a depth-first search

- $\bullet \Rightarrow$  tree edges
- non-tree edges

# <span id="page-16-0"></span>[Iterative counting](#page-16-0)

### Recursive versus iterative counting

### In my CLA'20 talk [Latin'20]: recursive counting



#### Recursive versus iterative counting

In my CLA'20 talk [Latin'20]: recursive counting

The time complexity (in the number of arithmetic operations) for partitioning the Boolean functions in k variables according to their ROBDD size is

 $\Omega(M_k^{1.5\cdot \log M_k}),$ 

where  $M_k$  if the largest ROBDD on  $k$  variables.

$$
(M_k)_{k=1,\ldots,12} = (3,5,7,11,19,31,47,79,143,271,511,767).
$$

We have  $\frac{2^k}{4}$  $\frac{2^k}{k} \leq M_k \leq 2 \cdot \frac{2^k}{k}$  $\frac{1}{k}$  as k tends to infinity.

In practice, we computed the partition for  $k = 8$  in about 2 hours on a personal computer with a python implementation and for  $k = 9$ , in several days using a fast computer with a  $C_{++}$  implementation. Today: iterative counting

through inclusion-exclusion principle



## Recursive versus iterative counting

## Today: iterative counting

#### through inclusion-exclusion principle



- 7 incoming edges
- 3 nodes
- 9 outgoing edges

Today: iterative counting

through inclusion-exclusion principle

The time complexity (in the number of arithmetic operations) for partitioning the Boolean functions in k variables according to their ROBDD size is

 $O(M_k^4 \cdot \log M_k),$ 

where  $M_k$  if the largest ROBDD on  $k$  variables.

 $(M_k)_{k=1,\ldots,12} = (3, 5, 7, 11, 19, 31, 47, 79, 143, 271, 511, 767).$ 

We have  $M_k \approx 2^k/k$  as  $k$  tends to infinity.

In practice, we compute the partition for  $k = 12$ , thus for the  $2^{4096}$  functions in about 6 hours on a computer with  $>$  200GB of RAM.

#### cf. <https://github.com/agenitrini/BDDgen>

## <span id="page-22-0"></span>[Unranking a ROBDD](#page-22-0)

- 1. Defining a total order over the structures (same number of Boolean variables and same size).
- 2. Constructing the structure only by using its rank.

- $\Rightarrow$  This allows to build structures of a given size.
- $\Rightarrow$  This leads trivially to a uniform (by size) random sampler.

Inputs: rank r, size s, number of variables k

1. Select the profile;

Done by iteratively computing the number of nodes by layer.

Inputs: rank r, size s, number of variables k

- 1. Select the profile;
- 2. Build the spine;

Reverse postorder traversal gives information about non-tree edges.

Inputs: rank r, size s, number of variables k

- 1. Select the profile;
- 2. Build the spine;
- 3. Build the ROBDD;

Inorder traversal allows to decide the destination of non-tree edges.

Inputs: rank r, size s, number of variables k

- 1. Select the profile;
- 2. Build the spine;
- 3. Build the ROBDD;

The unranking algorithm with inputs  $r, n, k$  satisfies:  $\bullet$   $O(k^2 n^5)$  time complexity and  $O(n^2)$  extra space for identifying the profile; •  $O(k^2 n^3)$  time complexity to generate the ROBDD with a given profile.

Inputs: rank r, size s, number of variables k

- 1. Select the profile;
- 2. Build the spine;
- 3. Build the ROBDD;

The unranking algorithm with inputs  $r, n, k$  satisfies:  $\bullet$   $O(k^2 n^5)$  time complexity and  $O(n^2)$  extra space for identifying the profile; •  $O(k^2 n^3)$  time complexity to generate the ROBDD with a given profile.

We can shortcut Step 1, or Step 1 and 2.





Same size as Majority with 15 variables.









Same spine as Majority with 15 variables.



## ROBDD gallery: same spine as Majority with 35 variables



## Conclusion and future work

- Our combinatorial approach adapts very well.
	- subclasses of functions: ex. only with essential variables
	- other classes of BDDs (with other constraint rules)
		- OBDDs
		- Quasi-reduced BDDs
		- Zero-supressed BDDs
- In the future:
	- Combinatorial characterization of the class of spines?
	- Can we improve the time complexity for the counting/unranking methods?